

B.VIII. Exponential Smoothing Methods

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Introduction

Exponential smoothing methods belong to the category of fast computational forecasting methods.

Advantages:

- ➊ Simple to implement: forecasting equations are easy to understand and compute.
- ➋ No underlying models.
- ➌ Methods often as performant as more sophisticated ones.
- ➍ Robust methods: may work on short series with possible structural changes.

Disadvantages:

- ➊ Not tailored to certain type of data.
- ➋ Arbitrary choice of smoothing constant.

Setup

Data: $Y_1, \dots, Y_t, \dots, Y_T$

We are at date T and wish to forecast the value Y_{T+h} at date $T + h$.

The *forecast value* is denoted $\hat{Y}_T(h)$, and h is called the *forecast horizon*.

Simple Exponential Smoothing

Parameter: $\alpha = \text{smoothing constant}$ satisfying $0 < \alpha < 1$.

Definition:

$$\hat{Y}_T(h) = (1 - \alpha) \sum_{j=0}^{T-1} \alpha^j Y_{T-j}$$

Remarks:

- ➊ Most recent observations have the greatest influence (exponential decay of influence of past data).
- ➋ α close to 1: large influence of past data (rigidity of forecast).
- ➌ α close to 0: small influence of past data (adaptivity to most recent data).
- ➍ Definition does not depend on h , thus we use notation \hat{Y}_T .

Simple Exponential Smoothing

Updating formulas:

$$\hat{Y}_T = \alpha \hat{Y}_{T-1} + (1 - \alpha) Y_T$$

This is a weighted average of forecast at date $T - 1$ and of the latest observation.

If α is small we get more weight to the latest observation

$$\hat{Y}_T = \hat{Y}_{T-1} + (1 - \alpha)(Y_T - \hat{Y}_{T-1}).$$

We have an error correction mechanism.

We need to initialize the algorithm. To do so, we may choose $\hat{Y}_1 = Y_1$, for example.

Simple Exponential Smoothing

Interpretation:

Assume that the series is approximately constant on the observation period

$$Y_t = a + u_t, \quad t = 1, \dots, T$$

We may estimate the constant a by weighted least squares

$$\min_a \sum_{j=0}^{T-1} \alpha^j (Y_{T-j} - a)^2$$

The weights decline exponentially when move back in time.

Simple Exponential Smoothing

Solution of minimization problem:

$$\hat{a} = \frac{1 - \alpha}{1 - \alpha^T} \sum_{j=0}^{T-1} \alpha^j Y_{T-j}$$

For T large enough, we get $\hat{a} \approx \hat{Y}_T$.

Hence \hat{Y}_T takes the interpretation of the constant which approximates best the series around T since the weight declines when moving away from T .

The method is only relevant when the series is approximately constant next to T (locally constant) and should be avoided otherwise, for example, in the presence of a trend.

Simple Exponential Smoothing

Choice of the smoothing constant:

- 1 Subjective: depending of willingness to have fast adaptivity or more rigidity.
- 2 Choice advocated by Brown (inventor of the method):
 $\alpha = 0.7$.
- 3 Objective: constant chosen to minimize the sum of squared forecast errors

$$\sum_{t=1}^{T-1} \left(Y_{t+1} - \hat{Y}_t \right)^2.$$

Double Exponential Smoothing

Simple exponential smoothing adapted to locally constant series (constant = horizontal line).

Generalization:

Take a line with a slope (trend)

$$Y_t = a_1 + (t - T)a_2 + u_t.$$

We may use to forecast

$$\hat{Y}_T(h) = \hat{a}_1(T) + h\hat{a}_2(T).$$

The coefficients $\hat{a}_1(T)$, $\hat{a}_2(T)$ are obtained by solving :

$$\min_{a_1, a_2} \sum_{j=0}^{T-1} \alpha^j (Y_{T-j} - a_1 + a_2 j)^2.$$

Double Exponential Smoothing

For large T , we get

$$\begin{aligned}\hat{a}_1(T) &= 2S_1(T) - S_2(T), \\ \hat{a}_2(T) &= \frac{1-\alpha}{\alpha} (S_1(T) - S_2(T)),\end{aligned}$$

where $S_1(T)$ is the smoothed series

$$S_1(T) = (1 - \alpha) \sum_{j=0}^{T-1} \alpha^j Y_{T-j}$$

and $S_2(T)$ is the doubly smoothed series

$$S_2(T) = (1 - \alpha) \sum_{j=0}^{T-1} \alpha^j S_1(T - j).$$

Double Exponential Smoothing

Updating formulas used in practice:

$$\begin{aligned}\hat{a}_1(T) &= \hat{a}_1(T-1) + \hat{a}_2(T-1) + (1-\alpha^2) \left(Y_T - \hat{Y}_{T-1}(1) \right), \\ \hat{a}_2(T) &= \hat{a}_2(T-1) + (1-\alpha)^2 \left(Y_T - \hat{Y}_{T-1}(1) \right).\end{aligned}$$

Last terms are proportional to *error forecast* $Y_T - \hat{Y}_{T-1}(1)$
If perfect forecast $Y_T = \hat{Y}_{T-1}(1)$, i.e., forecast error is zero,
then there is no need to update, and we get:

$$\begin{aligned}\hat{a}_1(T) &= \hat{a}_1(T-1) + \hat{a}_2(T-1), \\ \hat{a}_2(T) &= \hat{a}_2(T-1).\end{aligned}$$

Initialization values:

$$\hat{a}_1(2) = Y_2, \quad \hat{a}_2(2) = Y_2 - Y_1.$$

Double Exponential Smoothing

Remark:

There exist other exponential smoothing methods which use two smoothing parameters:

- More adaptive such as the Holt-Winters method.
- May take into account the presence of seasonality, etc . . .